

# **H5U Series**

# High performance, compact, EtherCAT-enabled PLC

- · Compact footprint
- · PLCopen-compliant axis control
- · Simulation mode for offline debugging
- · Real-time fieldbus



# **H5U: high performance PLC**

### **Programming**

- · Supports function block and function for encapsulation, code reusability, and scalability
- · Efficient and easy-to-use ladder diagram programming, supporting graphic block instructions
- · User-defined variable programming with intuitive programming input assistant

#### **Motion control**

- · EtherCAT: 32-axis PTP motion control
- · PLCopen-compliant axis control
- · Local pulse and EtherCAT axis share the same motion control instructions
- · Axis group for lineal and circular interpolation
- · CAM tables functionality
- · 4 x high speed pulse output channels, to control stepper motors
- · Able to control servo drive via CANopen

#### **Communications**

- · Supports 72 EtherCAT slaves
- · 1 CAN interface: CANopen and CANlink master/slave
- · 1 RS485 interface: Modbus RTU master/slave
- · 1 Ethernet connection supports Modbus TCP and socket programming instructions

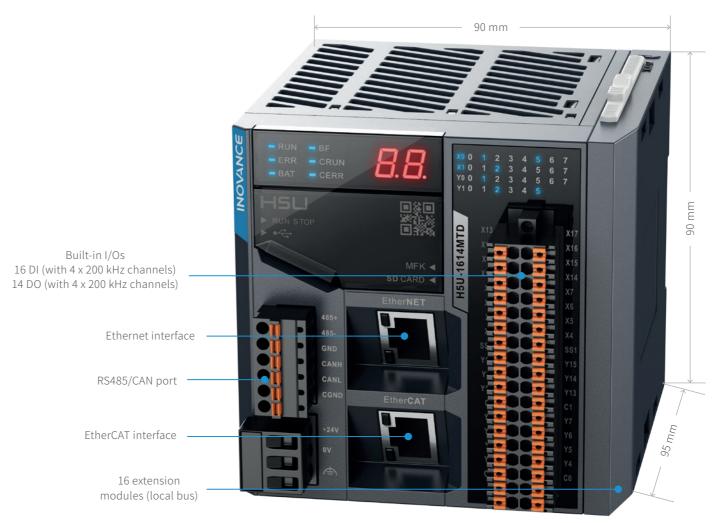
## I/O configuration

- · Main unit with 16 inputs and 14 outputs, including high-speed I/Os
- · Supports up to 16 GL10 (AM600 series) local expansion modules
- · Remote GR10 I/O modules can be connected as EtherCAT slaves

Please note: refer to AM600 catalogue for more detail about our remote I/O modules

## Commissioning

- · Simulation mode
- PLC programs
- Axis control
- Local I/O
- Serial and Ethernet comms
- · High-resolution trace tool
- · Program upload/download and firmware upgrade (only available with SD card)
- · Axis interface for easy test and monitoring



This image is illustrated in its actual size: W 90 mm x H 90 mm x D 95 mm

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Model	H5U-1614MTD
Axis capacity	A total of 32 synchronised axes is possible. This can be a max. of 32 EtherCAT axes <sup>1</sup> , or a combination that includes a max. of four pulse control axes
Communication specifications	EtherCAT: max. 72 EtherCAT slaves <sup>2</sup> (including synchronised axes)
	Ethernet: Modbus TCP, socket programming
	CAN: supports CANlink and CANopen (only supports CANopen for axis control)
	RS485: Modbus RTU and free communication protocol
Program capacity	200 K-step user program
Data capacity	2 MB user-defined variables, of which 256 KB supports power failure retention
	Approx. 150 KB soft elements, of which 145 KB supports power failure retention
Programming language	LD, SFC, supporting function block/ function (LD)
High-speed I/Os	4 x 200 kHz high-speed inputs (2 encoder counting)
	8 x 200 kHz high-speed outputs (4-axes pulse output)
General I/Os	16 sink (NPN)/ source (PNP) inputs and 14 sink (NPN) outputs (including high-speed I/Os)
Module expansion	16 local modules, remote modules can be connected as EtherCAT slaves
Power input	+24 VDC
Other interfaces	USB SD card
Dimensions	L x W x H = 83 mm x 95 mm x 90 mm
Ordering code	01440087

<sup>&</sup>lt;sup>1</sup>Synchronised axes

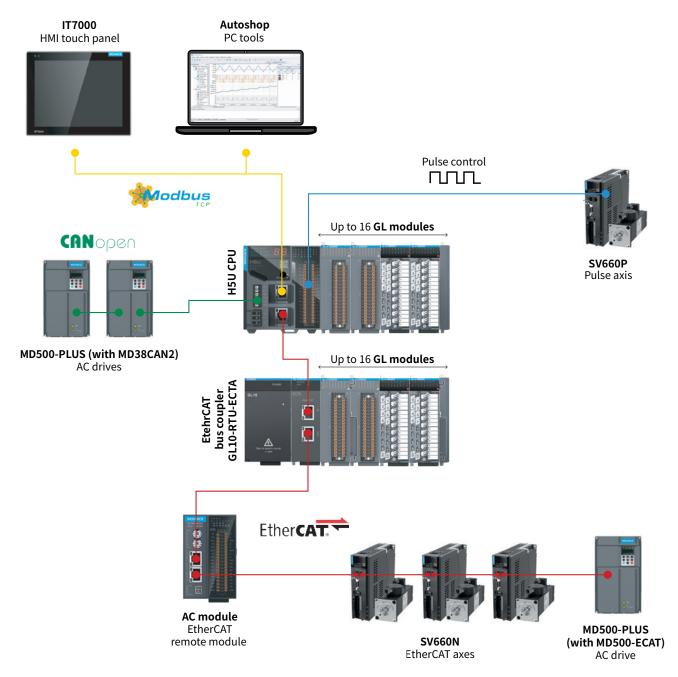
 $<sup>^{2}\</sup>mbox{EtherCAT}$  slaves include I/Os and synchronised and non-synchronised axes







# **H5U - application topology**



For more information, please contact our local offices.



- Germany-Stuttgart
  - Tel: +49 (0) 7144 8990 sales.de@inovance.eu
- Italy-Milano

Tel: +39 (0) 2268 22318 | sales.it@inovance.eu

France-Bordeaux

Tel: +33 (0) 5594 01050 | sales.fr@inovance.eu

Turkey-Istanbul

Tel: +90 (216) 706 17 89 | info@inovance.eu

Hong Kong SAR

International Export Office Tel: +852 2751 6080 info@inovance.eu South Korea-Seoul

Tel: +82 (0) 10 7428 5732 | info@inovance.eu

India

Head Office Chennai | Tel: +91 (0) 44 4380 0201 Ahmedabad | Tel: +91 (0) 79 4003 4274 Mumbai | Tel: +91 (0) 22 4971 5883 New Delhi | Tel: +91 (0) 11 4165 4524 Sales Network in Kolkata, Bengaluru, Coimbatore, Hyderabad, Pune, Vadodara

Email: info@inovance.ind.in

For other country distributors, contact the Hong Kong office.

### **Inovance Technology Companies**

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